

A 96.6%-Peak-Efficiency 4.63-A/mm³-Peak-Density Resonant-Tank Converter with RDL Trace Inductor and Trajectory Control for Vertical Power Delivery

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Abstract—A resonant-tank converter with RDL trace inductor and Phase-Shifted Trajectory Control is proposed to achieve ultra-high-density vertical power delivery for high-performance computing (HPC). Fabricated in a 65-nm CMOS process with flip-chip assembly, it achieves 96.6% peak efficiency and 4.63-A/mm³ peak density with stable closed-loop regulation.

Index Terms—Resonant-tank converter, RDL trace inductor, trajectory control, vertical power delivery

I. INTRODUCTION

With the rapid emergence of versatile AI technologies and the proliferation of digital content, a revolutionary power supply architecture is pivotal for powering large-scale, high-performance computing (HPC) processors. Regarding point-of-load (PoL) conversion, the ever-increasing and dynamically changing HPC power requires both high power density and rapid load response. A ring-type converter architecture is gaining significant attention for its inherent current balance and scalability [1]–[3]. However, excessive use of bulky, high-Q inductors poses substantial integration challenges for vertical power delivery (VPD). In this paper, a Stacked-Ladder Resonant-Tank converter (ReLA) with vertical scalability fundamentally resolves the VPD integration challenge. As shown in Fig. 1(a), the proposed ReLA is fully packaged in a 2.5D flip-chip assembly, with flying/decoupling capacitors and RDL trace inductors vertically integrated into an ultra-thin interposer. It can also be configured as a 3D architecture (Fig. 1(b)), thereby reducing regulation latency and IR drop. Furthermore, the proposed ReLA also provides lateral scalability through a ring-type extension.

II. OVERALL ARCHITECTURE

Fig. 2 illustrates the overall architecture of the proposed ReLA ring, where every two adjacent phases are paired with complementary current flows for cross-phase charge balance without mid-rail DC capacitors (C_{MID}). A shared back ring enables one-shot activation/deactivation of ReLA phases at the

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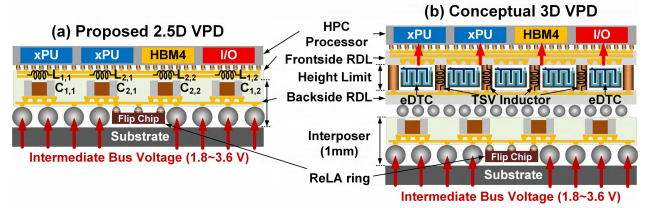


Fig. 1. (a) Proposed 2.5D VPD architecture using RDL trace inductors; (b) Conceptual 3D VPD architecture built of TSV inductors & DTCS.

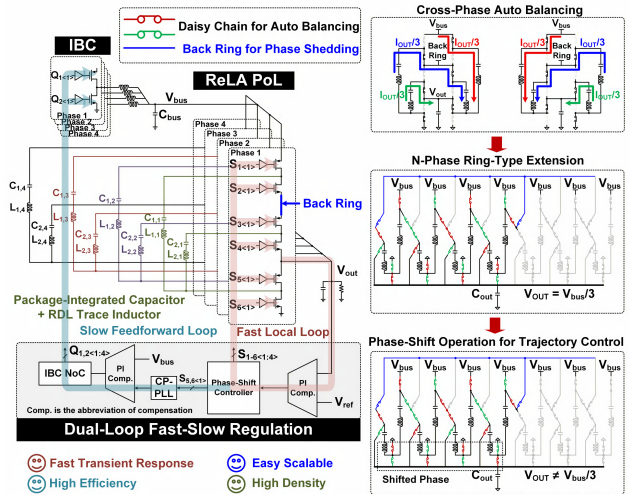


Fig. 2. Overall architecture of the proposed ReLA ring (left); proposed cross-phase auto-balancing, N-phase ring-type extension, and phase-shift operation for trajectory control (right).

zero-current crossing (ZCS) points. Furthermore, the ReLA ring can be reconfigured into “Boost” or “Buck” trajectory-control modes using high-frequency phase-shift modulation to maintain a stable V_{OUT} . Furthermore, the phase-shift information is fed forward to regulate the IBC bus voltage (V_{BUS}) and retain the nominal voltage conversion ratio (VCR), thereby maintaining ultra-high steady-state efficiency [4].

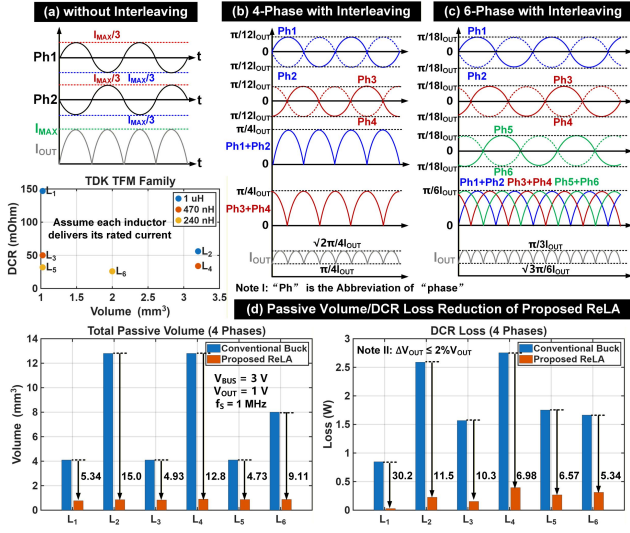


Fig. 3. (a) Conceptual waveforms (a) without phase interleaving, (b) with 4-phase interleaving, and (c) with 6-phase interleaving. (d) Passive volume/DCR loss reduction of the proposed ReLA ring.

III. INTERLEAVED RIPPLE SUPPRESSION

Fig. 3(a) shows the conceptual waveform of the proposed ReLA under complementary two-phase operation. The cross-phase auto-balance enables finer current splitting than conventional resonant topologies [5]–[7], thereby achieving a current reduction ratio (I_L/I_{OUT}) of $2/3N$ ($N = 2, 4, 6, \dots$). With N -phase interleaving, the proposed ReLA ring achieves similar ripple cancellation as a conventional multi-phase Buck (MPB) converter (Fig. 3(b-c)). By using RDL trace inductors, the proposed ReLA ring achieves up to 15(30) times reduction in total passive volume (DCR loss) compared to MPB under the same V_{OUT} ripple constraint and rated I_L (Fig. 3(d)).

IV. PHASE-SHIFTED TRAJECTORY CONTROL

Fig. 4 shows the proposed nominal switching states and those for phase-shift operation (Mode I/II). The conceptual waveforms of “Boost” and “Buck” operating modes are illustrated in Figs. 5(a) and 5(b), respectively. While the equivalent trajectories of nominal operation are circles centered at (1,0) on the state plane [8], the proposed phase shift operation (Mode I/II) evokes cross-circle leaps centered at (2,0) or (0,0). As a result, the proposed Phase-Shifted Trajectory Control compensates for load-regulation damping and maintains the target V_{OUT} regardless of the varying I_{OUT} .

V. MODULAR HANDSHAKE DRIVING

To fully exploit the intrinsic DC rails of the ReLA topology, a Modular Handshake Driving technique is proposed as shown in Fig. 6(a). The gate-driving signals for each CMOS pair are fed back locally (inner loop) and combined with the level-shifted turn-on/off signals to enable non-overlapping switching. In the outer loop, the raw turn-off signals are generated in the core-voltage domain and level-shifted upward

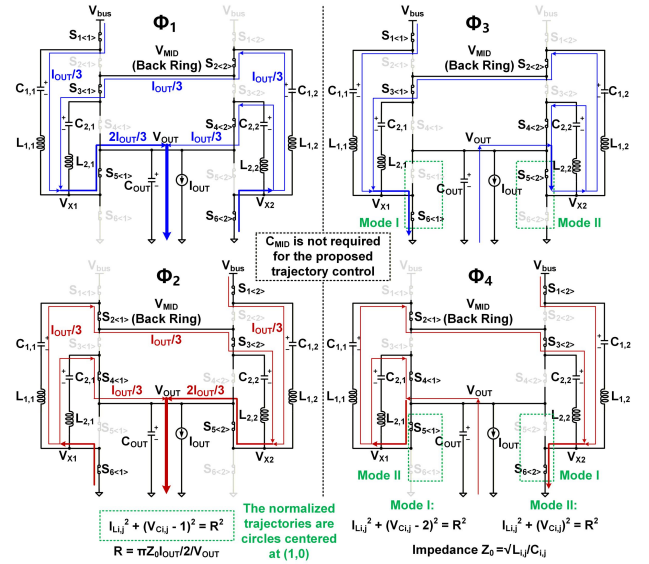


Fig. 4. Proposed nominal switching states (left) and those for phase-shift operation (right) with corresponding trajectory equations.

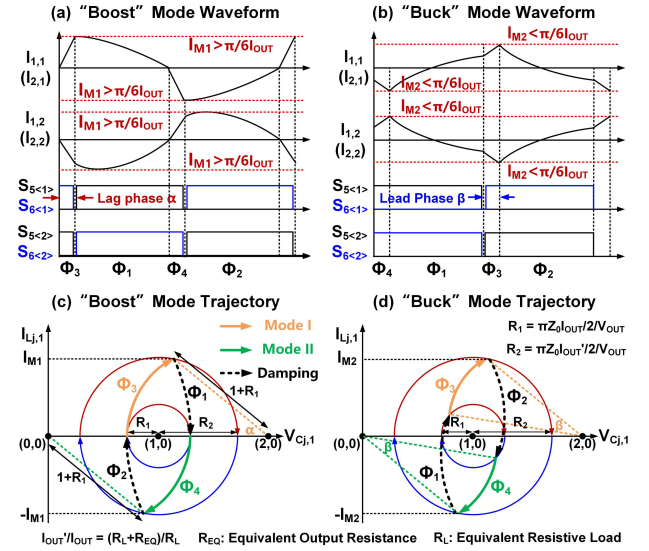


Fig. 5. Conceptual waveforms of (a) “Boost” mode & (b) “Buck” mode, and trajectories of (c) “Boost” mode & (d) “Buck” mode.

in the same direction as the voltage stacking. Then, the gate-driving signals at the highest stack level are level-shifted in the opposite direction to ensure non-overlapping switching between inter-level power switches. By using the Vertical Scalable Level Shifter [9], the proposed ReLA is implemented by low-voltage devices exclusively (Fig. 6(b)). Furthermore, a phase-shedding arbiter, cooperated with the proposed daisy chain configuration, enables one-shot activation/de-activation of ReLA phases at the ZCS points (Fig. 6(c)).

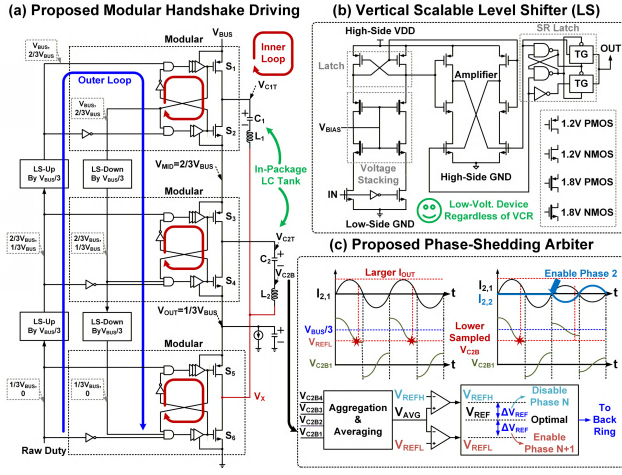


Fig. 6. (a) Proposed Modular Handshake Driving technique for ReLA ring; (b) Vertical scalable level shifter for power-stacking module; (c) Proposed one-shot phase-shedding arbiter.

VI. MEASUREMENT RESULTS

Fig. 7 shows the FCCSP die photo of the proposed ReLA. The inter-phase power traces are symmetrically redistributed to the integrated passive devices (IPDs). Each RDL trace inductor is tuned at a nominal value of 5.6 nH through silicon-interposer co-design, and the estimated ACR at 1 MHz is 7.9 m Ω . To comply with the 1-mm interposer height constraint, flying/decoupling capacitors are all in 0201 footprints.

Fig. 8(a) shows the measured steady-state waveforms of the switching nodes. The measured inductor waveforms under nominal, “Boost”, and “Buck” operating modes are highly consistent with the theoretical analysis (Fig. 8(b)). As shown in Fig. 8(c), the phase-shedding command is issued every five switching cycles. At the ZCS point, the number of activated ReLA phases is adjusted in a single shot, as expected.

Under 4-phase interleaved operation, the V_{OUT} ripple is approximately reduced by half compared to that under 2-phase operation (Fig. 9(a)). Fig. 9(b) shows the measured transient waveforms with a 1-A I_{OUT} step. With the proposed Phase-Shifted Trajectory Control, the V_{OUT} undershoot and overshoot are clamped within 127.5 mV and 129.6 mV, respectively. At the nominal VCR, the proposed ReLA ring achieves peak power conversion efficiencies (PCE) of up to 96.6% (Fig. 9 (c)), with V_{OUT} varying from 0.8 V to 1.2 V. The 2-phase prototype delivers a maximum I_{OUT} of 4.23 A at a V_{OUT} of 1.2 V and sustains 79.5% PCE under full load.

Fig. 10 and Table I compare state-of-the-art (SOTA) high-density PoL designs [4], [10]–[13]. The proposed ReLA ring achieves the best peak density of 1.66 A/mm² (equivalent to 4.63 A/mm³) and a comparable peak PCE of 96.6%.

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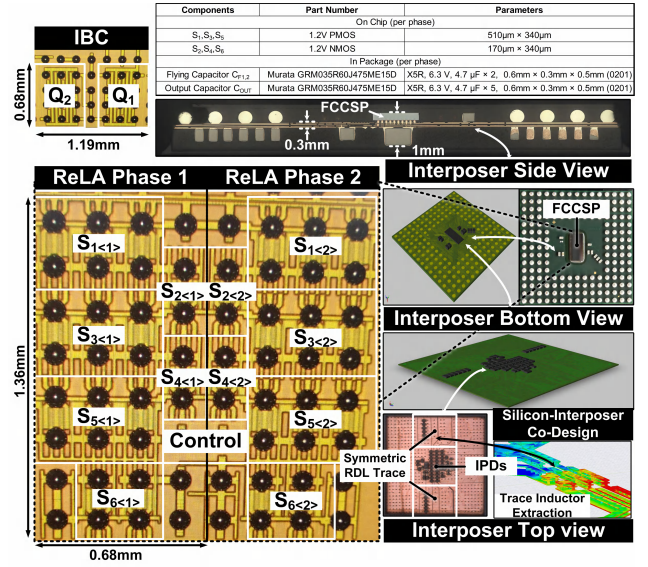


Fig. 7. On-chip/in-package component list of the proposed ReLA (top), FCCSP die (left), and interposer photos (right).

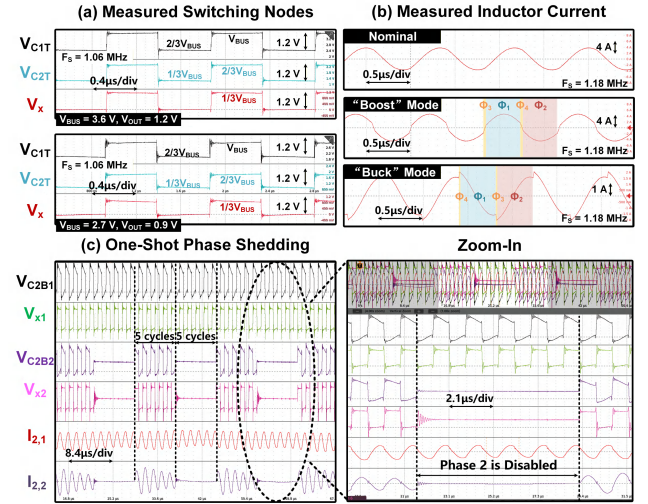


Fig. 8. (a) Measured steady-state switching-node voltages; (b) Measured inductor current waveforms in different operating modes; (c) Measured one-shot phase shedding at the ZCS points.

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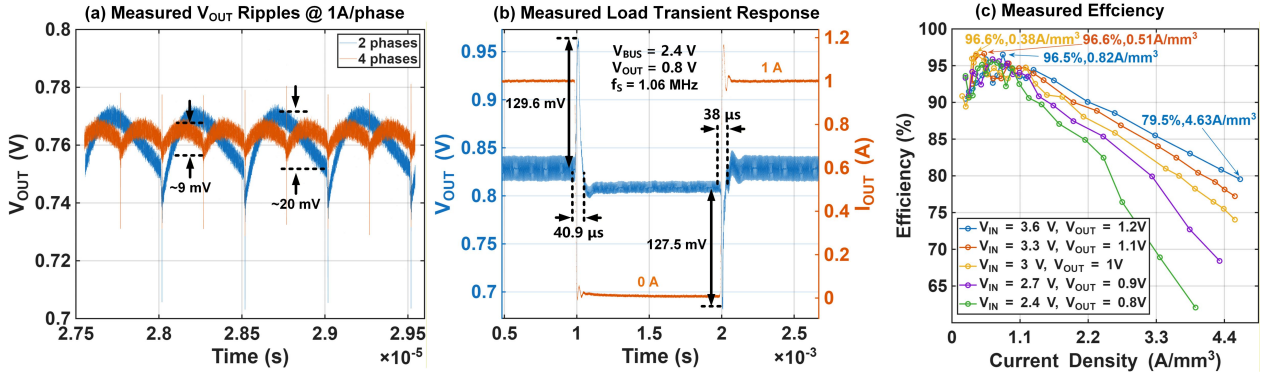


Fig. 9. (a) Measured V_{OUT} ripple suppression with phase interleaving, (b) measured 1-A load transient response, and (c) measured efficiencies with scaled V_{OUT} and current densities.

TABLE I
COMPARISON WITH STATE-OF-THE-ART (SOTA) POL DESIGNS.

	ISSCC'22 [10]	VLSIC'23 [11]	VLSIC'24 [12]	ISSCC'24 [13]	ISSCC'25 [4]	This Work
Process	180nm BCD	180nm BCD	180nm BCD	28nm	65nm	65nm
Topology	Parallel SC	OISC	ABDP	Parallel SC	Resonant SC	ReLA
V_{BUS} (V)	3-4.2	1.5-3.3	1.8	3-3.6	2	1.8-3.6
V_{OUT} (V)	0.6-1	0.8-1.8	0.2-1.5	0.6-1	0.6-1	0.6-1.2
f_{SW} (MHz)	2	1 or 2	1	2	9	1.06 - 1.18
No. of Phases	1	2	1	1	6	2,4,6
Max. I_{OUT} (A)	1.2	1.55 (per phase)	2.5	1.5	2 (per phase)	2.12 (per phase)
Inductor Value	470 nH	1 μ H	470 nH	560 nH	850 pH	5.6 nH
Inductor DCR	N.R.	144 m Ω	N.R.	N.R.	N.R.	7.9 m Ω
Inductor Type	SMD	SMD	SMD	SMD	PCB Trace	RDL Trace
Inductor Volume	1.02mm ³	2mm ³	1.02mm ³	1.02mm ³	N.A.	N.A.
I_L/I_{OUT}	1/(1+2D) or 1/(1+D)	1/2/(2-D)	Fixed 2/3	2/(3D+2)	No	2/3 @ 3:1
C_{FLY} (per phase)	$2 \times 4.7 \mu$ F	$2 \times 4.7 \mu$ F	$2 \times 10 \mu$ F	10μ F + $2 \times 4.7 \mu$ F	1 μ F	$2 \times 4.7 \mu$ F
C_{OUT} (μ F)	10 μ F	0	10 μ F	10 μ F	$2 \times 10 \mu$ F	$5 \times 4.7 \mu$ F
Peak Efficiency	92.9%	97.3%	94.2%	94.1%	96.0%	96.6%
V_{IN} (V) & V_{OUT} (V)	3 & 0.8	3.3 & 1.8	1.8 & 1.2	3.3 & 1	2 & 1	3 & 1
Efficiency	82.0%	90.1%	75.0%	82.0%	84.0%	79.5%
I_{MAX} & V_{OUT}	1.2A & 0.6V	3.1A & 1.8V	2.5A & 0.9V	1.5A & 0.6V	6A & 0.6V	4.23A & 1.2V
Die Area (per phase)	2.72 mm ²	3.81 mm ²	4 mm ²	3.08 mm ²	1.06 mm ²	0.93 mm ²
Total Area ^a (per phase)	4 mm ²	12.19 mm ²	6.28 mm ²	5.64 mm ²	1.56 ^b mm ²	1.28 mm ²
Max. Current Density	0.3 A/mm ²	0.25 A/mm ²	0.398 A/mm ²	0.266 A/mm ²	1.282 A/mm ²	1.656 A/mm ²

^aTotal Area = Die Area + Inductor Area + C_{FLY} Area

^bAssume 0204 Capacitor is Used

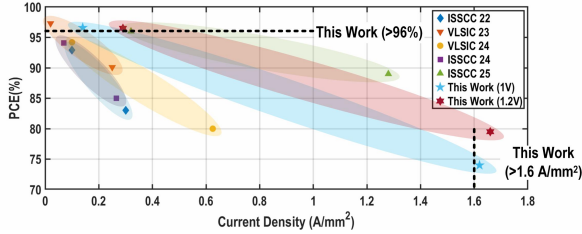


Fig. 10. Efficiency/density trade-offs of SOTA designs.

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